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Report TW 455, April 2006



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Abstract

For the manufacturing of composite materials with textile reinforcement, the permeability of the textile is a key characteristic. Using the law of Darcy, permeability can be derived from a numerical simulation of the fluid flow, i.e. by solving the Navier-Stokes or Brinkman equations. In this report we present the results of simulations with two different flow solvers: a finite difference Navier-Stokes/Brinkman solver and a lattice Boltzmann solver. The results are validated with theory and experimental data.

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Computation of the permeability of textiles

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Summary. For the manufacturing of composite materials with textile reinforcement, the permeability of the textile is a key characteristic. Using the law of Darcy, permeability can be derived from a numerical simulation of the fluid flow, i.e. by solving the Navier-Stokes or Brinkman equations. In this paper we present the results of simulations with two different flow solvers: a finite difference Navier-Stokes/Brinkman solver and a lattice Boltzmann solver. The results are validated with theory and experimental data.

1 Introduction

Liquid Composite Molding (LCM) is a manufacturing process which involves: laying up a textile reinforcement in a mold cavity of a desired 3D shape; injection of a liquid resin; polymerisation (for thermosets) or solidification (for thermoplasts) of the resin [15]. For the manufacturing of composites with textile reinforcement, the permeability of the textile is a key characteristic and is of particular importance for the injection stage of LCM. The prediction of textile permeability gained importance due to the often encountered problems of non-uniform impregnation, void and dry spot formation.

The permeability is a geometric characteristic related to the structural features of the textile at several length scales. Textiles are porous media and the permeability tensor is defined by Darcy's law

$$\langle \mathbf{u} \rangle = -\frac{1}{\nu\rho} \mathbf{K} \cdot \nabla \langle p \rangle, \quad (1)$$

with $\mathbf{u} = \mathbf{u}(x, y, z)$ the fluid velocity, ν and ρ the fluid viscosity and density, $p = p(x, y, z)$ the pressure, $\langle \cdot \rangle$ volume averaging and \mathbf{K} the permeability tensor of the porous medium. Equation (1) is a homogenised equation, and the information of the internal geometry of the reinforcement is taken into account in \mathbf{K} . Finite element or finite difference Darcy solvers require \mathbf{K} as input.

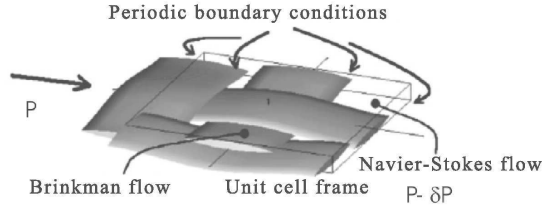


Fig. 1. A unit cell setup.

Unfortunately, the measurement of textile permeability is time and resource consuming [11], hence reliable numerical prediction of \mathbf{K} is required.

For the computation of \mathbf{K} , we can determine the flow in a unit cell, since textile has a periodic pattern (Fig. 1). As textiles are also hierarchically structured materials, our model for fluid flow must take the possible porosity of the material's yarns into consideration. Hence in the following, we will differentiate between inter-yarn flow (the yarns of the textile are solid) and intra-yarn flow (the yarns are porous and the porosity is accounted for by the permeability tensor \mathbf{K}_{tow}). In both cases we aim at a computation of the fluid velocity \mathbf{u} and the pressure p in order to solve Darcy's law (1) for \mathbf{K} .

In case the model is limited to creeping, single-phase, isothermal, unidirectional saturated flow of a Newtonian fluid, the inter-yarn flow is described by the incompressible Navier-Stokes equations,

$$\begin{cases} \frac{D\mathbf{u}}{Dt} = \frac{\partial\mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla)\mathbf{u} = -\frac{1}{\rho}\nabla p + \nu\Delta\mathbf{u} \\ \nabla \cdot \mathbf{u} = 0. \end{cases} \quad (2)$$

The first equation states the conservation of momentum (momentum equation), the second equation states the conservation of mass (continuity equation). Intra-yarn flow depends on the local permeability tensor of the tow \mathbf{K}_{tow} , and is described by the Brinkman equations [17] without neglecting the convection,

$$\begin{cases} \frac{\partial\mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla)\mathbf{u} + \nu\mathbf{K}_{tow}^{-1} \cdot \mathbf{u} = -\frac{1}{\rho}\nabla p + \nu\Delta\mathbf{u} \\ \nabla \cdot \mathbf{u} = 0, \end{cases} \quad (3)$$

where $\mathbf{u} = \mathbf{u}(x, y, z, t)$ and $p = p(x, y, z, t)$ for both the Brinkman and the Navier-Stokes equations. We assume ν and ρ to be constant when describing an incompressible, Newtonian fluid and thus also in the Darcy equation (1) for the computation of \mathbf{K} .

A key task in permeability modelling is the characterisation of the reinforcement. For the creation of a single layer model of the reinforcement, we use the WiseTex software [12, 13]. In practise however, often the permeability of a multi-layered reinforcement is required. Building the geometry model of a

multi-layered reinforcement is a complex additional step, for which the LamTex software has been developed [14]. The results of WiseTex and LamTex provide the input for the flow simulation tool.

We develop a software package, FlowTex, for the computation of the permeability tensor of textiles. A first version of FlowTex, based on a lattice Boltzmann model for fluid flow, has been tested and validated [4]. In this article we discuss our new module for FlowTex, based on a finite difference discretisation of the Navier-Stokes equations (2) and the Brinkman equations (3). Furthermore, we briefly explain the lattice Boltzmann model. Results of the permeability predictions with both models are compared and validated with analytical results for a model problem and with experimental data. Note that experimental validation is often missing in papers describing other software for permeability prediction.

2 Numerical approach

2.1 Finite difference discretisation

Solution of the Navier-Stokes equations

For flow simulations in the irregular geometry of a textile, we have chosen to solve equations (2) numerically on a regular staggered grid with a finite difference discretisation. An example of a textile geometry and its discretisation on a regular grid is shown in Figure 2. In the staggered grid approach, the pressure is discretised at the center of the cells, while the velocities are discretised on the edges. This discretisation leads to a strong coupling between pressure and velocities, and therefore avoids the occurrence of unphysical oscillations in the pressure. One could also use an irregular (unstructured) grid and a finite element or finite volume discretisation. However, generating the appropriate 3D meshes for complex textile geometries is difficult and time consuming for these methods.

Geometry issues and boundary conditions

If we neglect the intra-yarn flow, the yarns are treated as impermeable. Grid points can be in the fluid domain ('fluid points') or in the solid yarn domain ('solid points'). At the boundaries between the fluid and the solid, no-slip boundary conditions are set. We have chosen a linear approximation of the solution at the boundaries:

$$V_{i,j,k} = -V_{i+1,j,k},$$

where (i, j, k) denotes a solid point, and $(i + 1, j, k)$ denotes a fluid point. We use a second order discretisation of the Navier-Stokes equations, but since the

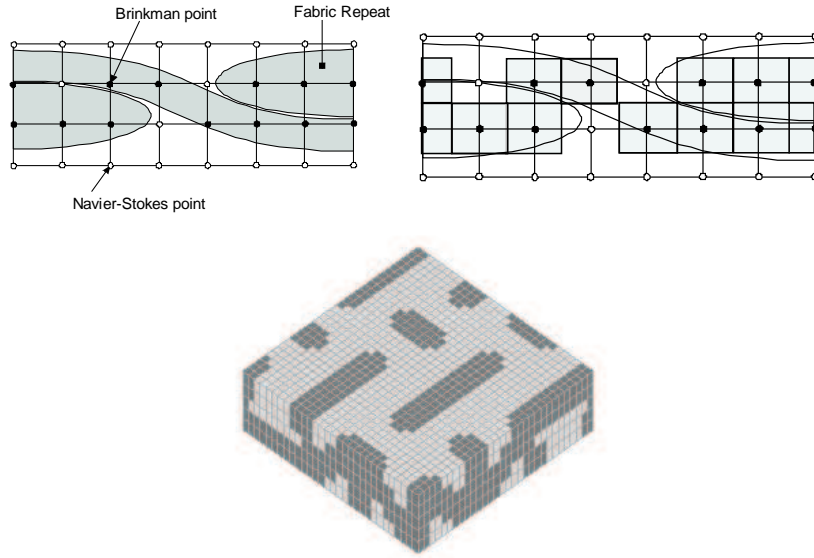


Fig. 2. Top: A 2D-textile model (left) and its first order approximation on the grid (right); bottom: 3D voxel geometry.

geometry is approximated to first order, we cannot expect second order accuracy near boundaries. Including a second order description of the geometry would not only lead to the geometry modelling problems that we avoid by using the finite difference method, but a second order approximation of the boundary imposes additional numerical stability problems. Using a first order approximation of the yarns means that fine meshes are required to obtain an accurate result.

Solution of the Brinkman equations

If we take the intra-yarn flow into account, the Brinkman equations (3) must be solved in the yarn points. Therefore the local permeability tensor \mathbf{K}_{tow} is first calculated by the formulae of Berdichevski [5] and Phelan [16]:

$$K_l = \frac{d^2}{32V_f} \left(\ln \frac{1}{V_f^2} - (3 - V_f)(1 - V_f) \right) \quad (4)$$

$$K_t = \frac{4d^2}{9\pi\sqrt{2}} \left(\sqrt{\frac{\pi}{4V_f}} - 1 \right)^{\frac{5}{2}} \quad (5)$$

The diameter d and the local fibre volume fraction V_f in the vicinity of the point, are provided by the WiseTex software. K_l is the permeability along the

fibre, K_t stands for the permeability across the fibre. WiseTex also provides the direction of the fibres. The orientation of the fibres determines how K_l and K_t form the entries of the tensor \mathbf{K}_{tow} .

The Brinkman equations (3) are similar to the Navier-Stokes equations (2), and the same discretisation methods are used. In (3) the additional term $\nu\mathbf{K}_{tow}^{-1}\mathbf{u}$ can be seen as a penalisation of (2). Equation (3) converges to equation (2) for large \mathbf{K}_{tow} . We solve the Brinkman equations on the whole domain with $\mathbf{K}_{tow} = \infty$ at fluid points while for yarns \mathbf{K}_{tow} is typically $10^{-4} \leq \mathbf{K}_{tow} \leq 10^{-7}$. This penalisation approach introduces a locally varying resistance force which leads to discontinuous velocities across the boundary between fluid and yarn points. To avoid numerical instabilities induced by this discontinuity, we apply a high order total variation diminishing (TVD) scheme for the convective terms discretisation.

Implementation

A finite difference Navier-Stokes solver, NaSt3DGP, was developed by the research group of Prof. Michael Griebel at the Institute for Numerical Simulation at the University of Bonn [9],[1]. The flow solver employs a Chorin projection for the solution of the Navier-Stokes equations (2). In time-discrete notation the projection method is given by:

Step 1: Solve the momentum equations for an intermediate velocity field \mathbf{u}^* :

$$\frac{\mathbf{u}^* - \mathbf{u}^n}{\Delta t} + [\mathbf{u} \cdot \nabla \mathbf{u}]^n = \nu \Delta \mathbf{u}^n \quad (6)$$

Step 2: Project the vector field \mathbf{u}^* on a divergence-free vector field \mathbf{u}^{n+1} :

$$\begin{cases} \mathbf{u}^* = \mathbf{u}^{n+1} + \Delta t \nabla p \\ \nabla \cdot \mathbf{u}^{n+1} = 0 \end{cases} \quad (7)$$

Applying the divergence operator to the first part of (7) results in a Poisson equation for the pressure which has to be solved in every time-step Δt . For the solution of the Poisson equation NaSt3DGP offers several iterative solvers like SOR, Red-Black Gauss-Seidel or BiCGStab. For the approximation of (6-7), the code provides several second order TVD upwind schemes for space discretisation and an explicit Euler as well as a second order Adams-Bashfort scheme for time discretisation. Furthermore, the code works completely in parallel on MPI [2] platforms.

Explicit treatment of the time-advancement of the momentum equations (6) yields a Courant-Friedrich-Levy (CFL) stability constraint for the convective terms, as well as a stability constraint for the diffusive terms depending strongly on the magnitude of the viscosity

$$\Delta t \leq \frac{1}{2\nu \Delta x^2}, \quad (8)$$

where Δx denotes the smallest grid resolution. This is a strong restriction on the time-step size, as in permeability computations we deal with Reynolds number $\text{Re} = \frac{1}{\nu} \approx 1$. In this low Reynolds number regime the CFL condition for the convective terms usually allows for a much larger time-step than (8). Therefore, it is desirable to treat the diffusive terms implicitly.

Semi-implicit solution of the Navier-Stokes equations

We opted for a second-order semi-implicit discretisation of the Navier-Stokes equations (2) given by

$$\begin{cases} \frac{\mathbf{u}^{n+1} - \mathbf{u}^n}{\Delta t} + [\mathbf{u} \cdot \nabla \mathbf{u}]^{n+\frac{1}{2}} + \nabla p^{n+\frac{1}{2}} = \frac{\nu}{2} \Delta (\mathbf{u}^{n+1} + \mathbf{u}^n) \\ \nabla \cdot \mathbf{u}^{n+1} = 0. \end{cases} \quad (9)$$

In this representation

$$[\mathbf{u} \cdot \nabla \mathbf{u}]^{n+\frac{1}{2}} = \frac{3}{2} \mathbf{u}^{n+1} \cdot \nabla \mathbf{u}^{n+1} - \frac{1}{2} \mathbf{u}^n \cdot \nabla \mathbf{u}^n$$

denotes an Adams-Bashforth approximation of the convective derivative at time $n + \frac{1}{2}$ and is computed explicitly, while the diffusive terms are discretised with the Crank-Nicolson scheme and are treated implicitly. With this scheme we avoid the restriction of the time step (8) as well as the solution of a nonlinear system of equations. Again, we use a fractional step method to solve (9). In order for \mathbf{u}^* to be a good approximation to the divergence-free velocity field \mathbf{u}^{n+1} , the pressure gradient is included in the momentum equations resulting in the following pressure-correction scheme as proposed by Bell et al. [3]:

Step 1: Solve the momentum equations for the intermediate velocity field \mathbf{u}^* :

$$\left(I - \frac{\nu \Delta t}{2} \Delta\right) \mathbf{u}^* = \mathbf{u}^n - \Delta t \cdot \{[\mathbf{u} \cdot \nabla \mathbf{u}]^{n+\frac{1}{2}} + \nabla p^{n-\frac{1}{2}} - \frac{\nu \Delta t}{2} \Delta \mathbf{u}^n\} \quad (10)$$

Step 2: Recover \mathbf{u}^{n+1} from the projection of \mathbf{u}^* by solving

$$\begin{cases} \mathbf{u}^* = \mathbf{u}^{n+1} + \Delta t \nabla \phi^{n+1} \\ \nabla \cdot \mathbf{u}^{n+1} = 0 \end{cases} \quad (11)$$

Step 3: The new pressure is now found by computing

$$p^{n+\frac{1}{2}} = p^{n-\frac{1}{2}} + \phi^{n+1} - \frac{\nu \Delta t}{2} \Delta \phi^{n+1} \quad (12)$$

The last term in this equation was introduced by Brown et al. [7] in order to be consistent with a second-order accurate discretisation of the Navier-Stokes equations. The pressure at time-level $n + 1$ can be recovered by an

extrapolation of the pressures obtained directly from the solution procedure at time-level $n + \frac{1}{2}$ and $n - \frac{1}{2}$

$$p^{n+1} = \frac{3}{2}p^{n+\frac{1}{2}} - \frac{1}{2}p^{n-\frac{1}{2}}. \quad (13)$$

Altogether, this kind of implicit treatment of the Navier-Stokes equations yields three modified Helmholtz equations (10) for the velocities in addition to the Poisson equation for the pressure. For the solution of these equations we employ an SSOR Preconditioned Conjugate Gradient Method. The step size is now only limited by the CFL condition and by accuracy considerations. Compared to the explicit solver, the extra computational costs per iteration for the semi-implicit solver do not outrun the gain due to the larger time steps: computations of the permeability can be obtained much faster with this method as will be shown in the next section.

Further Improvements

In order to perform permeability calculations, we have made several further extensions to the NaSt3DGP code. For the unit cell setup, we implemented periodic boundary conditions in three directions for the velocity, and periodic boundary conditions up to a constant gradient for the pressure (Fig. 1). Discretisation of the Brinkman equations leads to a straightforward implicit implementation of the additional term $\nu \mathbf{K}_{tow}^{-1} \mathbf{u}$ in the momentum equations (6).

Using the computed average velocity over the whole domain at steady state, the permeability \mathbf{K} is derived from Darcy's law (1). As a stopping criterion we use convergence of the permeability \mathbf{K} up to a predefined threshold ε . Furthermore, for the input of the geometry, an interface between WiseTex and the Navier-Stokes and Brinkman code has been developed.

2.2 Lattice Boltzmann Method

The lattice Boltzmann model (LBM) is a mesoscopic approach to fluid dynamics and is based on the solution of a Boltzmann equation on a regular grid. The LBM applies for a large scale of macroscopic equations. It has been shown that the LBM can be used to simultaneously solve Eqs. (2) and Eqs. (3) [18]. For our purpose, we have chosen to implement the permeability model based on the LBM D3Q19. Here, "Q19" describes the connectivity pattern of the 3D lattice: every cell is connected with its neighbour and its next-nearest neighbours.

A disadvantage of the LBM is the prescribed constant lattice step in all directions, which may result in unnecessary large lattice sizes. Note that this is not the case with the finite difference discretisation. The lattice of the LBM

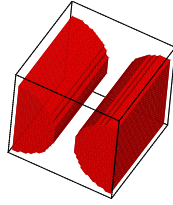


Fig. 3. Unit cell of the impermeable parallel square array with 60% volume fraction.

also contains three kinds of cells: fluid cells, solid cells and Brinkman cells. For the implementation of the non-slip boundary condition, the bounce-back rule is used. For the prediction of the flow in Brinkman cells, the local permeability is calculated as described in section 2.1 and then included in the LBM.

The described LBM has been implemented as a module for the FlowTex software at the K.U.Leuven. For more details on this module, we refer to [4].

3 Results and Validation

Validation tests with the lattice Boltzmann module and the finite difference module show good results. We present the results of the simulation of a flow through a parallel array of cylinders, and of two realistic reinforcements for which we have experimental verification. Forward Euler time-integration, and the VONOS [20] scheme for spatial discretisation was used in the finite difference method and its performance and accuracy will be compared to semi-implicit (Crank-Nicolson) time-integration. In both cases the BiCGStab [19] method with Jacobi preconditioning was used to solve the pressure Poisson equation.

3.1 Parallel Square Array

Impermeable Array

For the flow through a parallel array of impermeable tows (Fig. 3), theoretical, numerical and experimental data are available [21],[8]. Results can be found for different fibre volume fractions (V_f), i.e. different radii (R_f) of the cylinders. Figure 4 shows the theoretical permeability, together with the calculated permeability, both for flow along the cylinders and for transversal flow. The graph also shows a comparison between the permeabilities obtained with the finite difference Navier-Stokes solver and the lattice Boltzmann method. For the example of two volume fractions, Table 1 shows the calculated permeabilities for different grid spacings: the permeability converges, as Δx decreases.

Vf	Δx	#gridpoints	#iterations	K_{along}
20	0.1	1000	1200	0.05876
	0.05	8000	3900	0.04881
	0.03	35937	10100	0.04626
	0.025	64000	19100	0.04537
62	0.1	729	350	0.004906
	0.05	5832	850	0.003374
	0.03	27000	2100	0.003337
	0.025	46656	2950	0.003178

Table 1. Finite difference Navier-Stokes solver: results for the parallel square array setup: number of required iterations for the Poisson solver and computed permeability for different fibre volume fractions and mesh sizes.

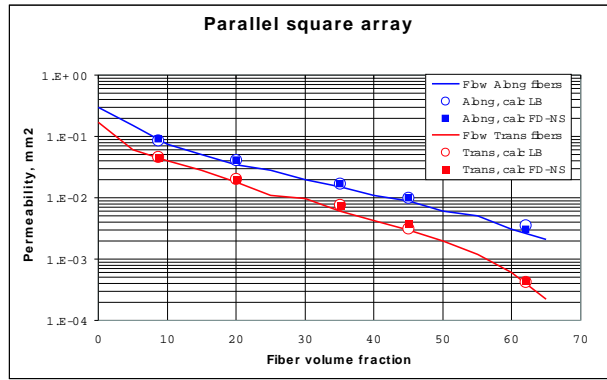


Fig. 4. Permeability for the parallel square array setup with different fibre volume fractions. Full lines: theoretical permeability; circles: lattice Boltzmann results; squares: finite difference Navier-Stokes results.

On a finer mesh more iterations for the Poisson solver are required (Table 1) because of two reasons. First, a finer mesh requires a smaller time-step, and therefore, more time-steps have to be taken. In the semi-implicit case the time-step may not be chosen much larger than the local mesh size, in order to obtain accurate results and in the explicit case it has to satisfy the even stronger restriction (8). Second, the preconditioned BiCGStab scheme for the Poisson equation converges more slowly to a solution on a finer mesh [6], so in each time-step more iterations are required.

Semi-implicit calculations

Semi-implicit and explicit time-stepping are compared for an impermeable array of cylinders with a fixed volume fraction of 60% (Table 2). Permeability calculations are carried out on a (40^3) grid. Stopping criterion is convergence

	Explicit	Semi-Implicit
#iter. Poisson	187713	14309
#iter. Helmholtz	0	893
Δt	$3.12 \cdot 10^{-5}$	$9.37 \cdot 10^{-4}$
$K_x (mm^2)$	$3.784 \cdot 10^{-3}$	$3.774 \cdot 10^{-3}$
Comp. Time	50m23s	03m37s

Table 2. Computational results of the semi-implicit Adams-Bashforth-Crank-Nicolson vs. the explicit Forward Euler method.

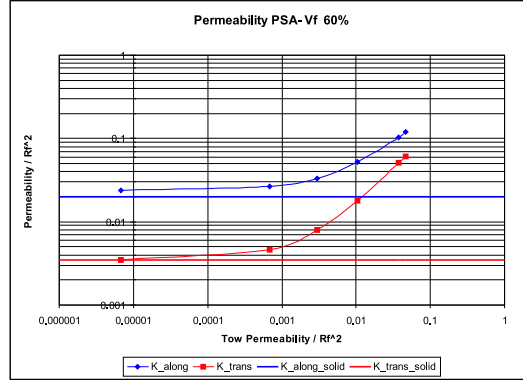


Fig. 5. Permeability of a Parallel Square Array with different local permeabilities.

of the permeability. Both calculations are performed on an Intel(R) Xeon(TM) CPU, 3.20GHz.

The time-step size for the semi-implicit calculations is 30 times larger than for the explicit case. This does not result in a speed up in computational time of the same factor because of the extra costs of solving three Helmholtz equations per time-step. Still, in this case, the implicit solver is about 14 times faster than the explicit solver. Both methods result in accurate permeability values.

Permeable array

Figure 5 shows the results of permeability predictions with the Brinkman solver. For a fixed volume fraction (60%), the permeability is calculated for different cylinder permeabilities \mathbf{K}_{tow} . For large \mathbf{K}_{tow} , the permeability of the unit cell increases to the permeability of an empty cell. As \mathbf{K}_{tow} decreases, the cylinders become more and more solid and the unit cell permeability converges to the permeability of an impermeable array.

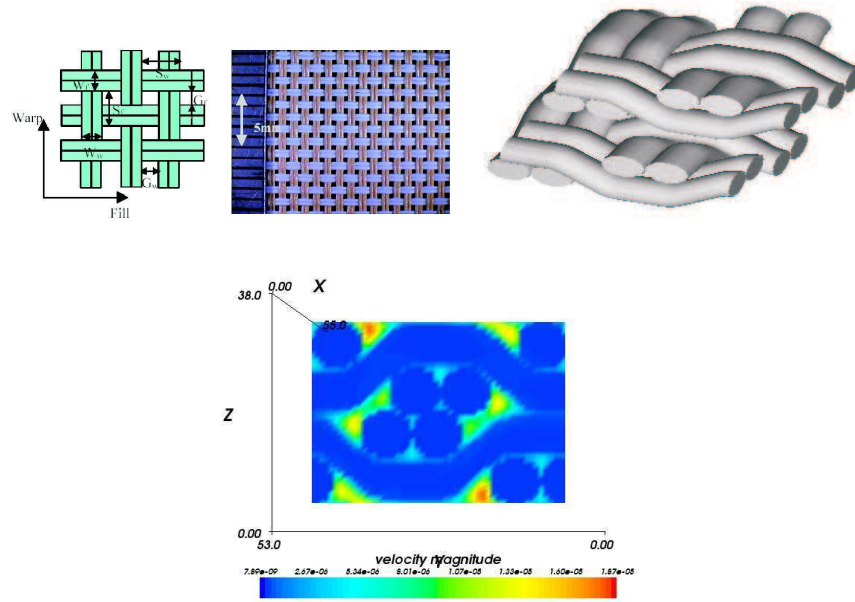


Fig. 6. Top: The Monofilament experimental setup and WiseTex model. Bottom: A 2D-cut of the simulated velocity field.

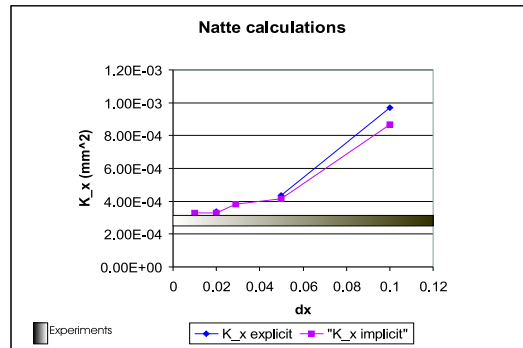


Fig. 7. Results of the Natte permeability calculations.

3.2 Monofilament fabric

The Monofilament fabric Natte 2115 is a more realistic structure which is close to actual textile reinforcements, and for which permeability is experimentally validated. The full description of the Monofilament Fabric Natte 2115 test-fabric can be found in [11],[10]. The yarns are impermeable, so the

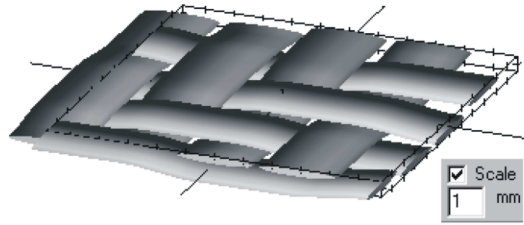


Fig. 8. WiseTex model of the carbon woven fabric.

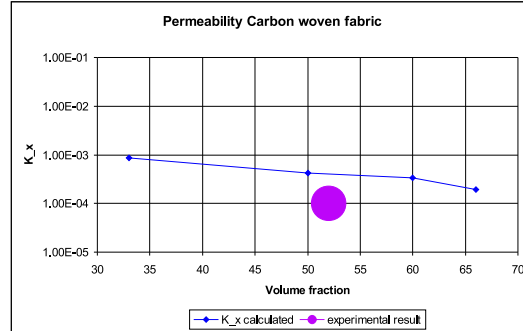


Fig. 9. Results of the carbon woven fabric permeability calculations.

Navier-Stokes equations are solved. Figure 6 shows the experimental setup, the WiseTex model and the flow velocity field in a 2D-cut. In the yarns and at the boundaries, the velocity is zero. The zero velocity surface shows a good approximation of the textile geometry. The flow was simulated for two layers of textile, which are maximally nested. Permeability calculations will give different results for one layer setups and for setups with minimal, average or maximal nesting.

Calculations are carried out with semi-implicit as well as explicit time-integration. Figure 7 shows that the predicted permeability depends strongly on the grid spacing. The first order discretisation of the geometry leads to a slightly different actual geometry. Hence on a coarse grid, we actually solve a different problem, which leads to a higher permeability. Furthermore, with semi-implicit time-stepping the calculated permeability is smaller than in the explicit case, but for a finer mesh this difference tends to zero.

3.3 Carbon woven fabric

A second structure is a Carbon woven fabric (Fig. 8). This woven fabric has a weave twill 2/2, warp/weft yarns 6K HR carbon flat rovings, ends/picks 3.5 yrns/cm and a (calculated) areal density of $282\text{g}/\text{m}^2$. The fabric model on

which calculations are performed, is provided by the LamTex software and contains three layers. On the fabric, pressure can be applied, which leads to different volume fractions of the textile. Figure 9 shows the results of the permeability calculations for different applied pressures and an experimental result. These results are obtained with a very fine discretisation in the z-direction, and could thus not be obtained with the LBM-module which requires a constant lattice step in all directions as mentioned in paragraph 2.2.

4 Conclusions

We presented a software package for the computation of the permeability of textile reinforcements.

First a textile model is designed with the WiseTex or LamTex software. An accurate model is required as slight differences in the model lead to different permeabilities. Using the model resulting from WiseTex or LamTex, flow simulations are performed to predict the permeability. We have chosen to solve the Navier-Stokes and Brinkman equations with the finite difference method and we compare the results with those obtained with a lattice Boltzmann method.

Both methods were validated on a parallel array of cylinders. For impermeable arrays, the calculated permeability can be compared with theoretical results. Both the finite difference Navier-Stokes and the lattice Boltzmann solver give accurate results for such setup. For permeable arrays theoretical results are not available, but the predictions of the Brinkman solver, including the intra-yarn flow, show good convergence to the results of the Navier-Stokes solver in case the permeability of the array tends to zero. To evaluate permeability calculations for real textiles, we presented validation results for a monofilament fabric Natte and a carbon woven fabric, for which experimental data are available.

In order to speed up permeability computations we implemented a semi-implicit pressure-correction method for the finite difference Navier-Stokes solver. With this numerical method a substantial reduction of computation time has been observed in all calculations.

5 Further research

Further validation of the software is necessary. Textile design engineers not only need correct permeability results, they also need them fast during the design process. Although the software is already useful for designing purposes, we will include more numerical improvements to speed up the calculations. The presented results are accurate. However, permeability is slightly overestimated. This may be due to the models used, which ignore physical phenomena (e.g. moving textile boundaries) as well as to the first order discretisation of

the boundaries. The improvement and extension of these models towards e.g. higher order boundary conditions is part of our ongoing research.

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